



## Outline

- Motivation
- Ontology-based activity recognition
- Handling uncertainty
- Hybrid data- and knowledge-driven methods
- Experiments
- Research challenges

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## Motivation

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## Which activities?

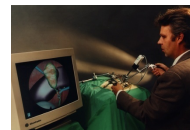
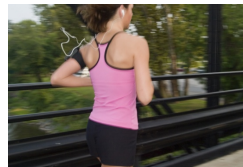
- Human activity recognition is about detecting:
  - Physical activities
  - Activities of daily living (ADL)
  - Social interactions

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## What for?

- Ubiquitous computing
- **Health-care**
- Recognition of critical events
- Training
- Homeland security



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## Based on what data?

- More invasive technologies
  - Camera, Microphone, Observers
- Less invasive technologies
  - Wearable sensors (smartwatch, smartphone, medical devices, ...)
  - Environmental sensors (position, time, temperature, object use, door openings, ...)
  - **Knowledge about the subject, the environment, the possible activities**

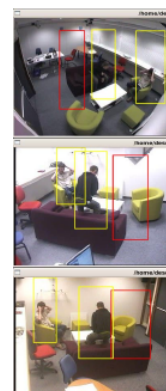
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## How?

### Statistical (data-driven) methods

- Based on the use of sound, image and scene recognition software
- Based on machine learning techniques and data coming from different sensors
  - Accelerometers
  - Body-worn sensors
  - Environmental sensors
  - RFID (objects' use)
  - ...



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## How?

### Symbolic (knowledge-driven) methods

- Human activities can be (imprecisely) formally described
- Given the description of a general activity (e.g., *giving a class*) an instance of that activity can be recognized from a set of facts (e.g., *20 students in classroom C1, Prof. Brown in C1, Prof. Brown using the blackboard, ...*) by firing some rules or by other reasoning mechanism

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## Why context/knowledge?

- Monitoring an anonymous professor ...
  - events from sensor readings :
    - reclining position (unchanged)
    - right arm reaching head (once every 2-3 minutes, span > 30min)
  - ARS can't find a good match

Sick in bed taking his hand periodically to the forehead for a headache?

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## Why context/knowledge?

- Add context:
  - it is Wed Sep 18, 3pm
  - his calendar says 'At DemAAL summerschool'

Revised guess:

- using microphone to ask questions in a seminar? (confidence low ...)



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## Why context/knowledge?

- Add context/data: picture posted on FB with timestamp Wed Sep 17 12:00



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## Why context/knowledge?

- use knowledge
  - load classifiers/descriptions for possible activities on the beach
  - use profile information (possibly with personal data mining)

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## Why context/knowledge?

- New activity candidate
  - relaxing and drinking beer on the beach (instead of improving his presentation)



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## How to use knowledge: the DL approach

- Description Logics (DL)
  - have a well-defined semantics
  - provide complete reasoning
  - are supported by optimized reasoning tools
- DLs are the underlying logics of OWL *ontology language*
- A domain is modeled by classes, individuals, and complex relationships among them
  - giving a class := the actor is a teacher,  
the actor's current location is a classroom,  
at least 5 students are in the classroom, and  
the actor is writing on a blackboard

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## DL Basics

- Terminologic Part (TBox)
  - A collection of concepts characterizing the domain (e.g., classes of activities, classes of context elements, types of actors/objects involved)
- Assertional Part (ABox)
  - A collection of facts about concrete instances in the application domain (e.g., specific objects, actors, locations observed)

The TBox is often referred as *ontology*  
TBox + ABox make the *knowledge base*

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## DL syntax

DL syntax and semantics of  $\mathcal{ALC}$ -concept descriptions and the corresponding OWL syntax.

constructor name	DL syntax	semantics	OWL syntax
negation	$\neg C$	$\Delta \setminus C^{\mathcal{I}}$	complementOf
conjunction	$C \sqcap D$	$C^{\mathcal{I}} \cap D^{\mathcal{I}}$	intersectionOf
disjunction	$C \sqcup D$	$C^{\mathcal{I}} \cup D^{\mathcal{I}}$	unionOf
existential restriction	$\exists r.C$	$\{x \in \Delta \mid \exists y : (x, y) \in r^{\mathcal{I}} \wedge y \in C^{\mathcal{I}}\}$	someValuesFrom
value restriction	$\forall r.C$	$\{x \in \Delta \mid \forall y : (x, y) \in r^{\mathcal{I}} \rightarrow y \in C^{\mathcal{I}}\}$	allValuesFrom

From [T. Springer et al, JAISE 2009]

$\text{Mother} \equiv \text{Person} \sqcap \text{Female} \sqcap \exists \text{has-child}.\text{Person}$

$\text{Person}(\text{Alice})$

$\text{Female}(\text{Alice})$

$\text{has-child}(\text{Alice}, \text{Marc})$

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## Higher expressivity with OWL2

$\text{TeaParty} \sqsubseteq \text{SocialActivity} \sqcap \forall \text{hasTimeExtent}.\text{Afternoon} \sqcap$   
 $\forall \text{hasActor} . (\text{Person} \sqcap \exists \text{hasCurrentPosture}.\text{Seated}$   
 $\sqcap \exists \text{hasCurrentActivity}.\text{Sipping} \sqcap \exists \text{hasCurrentLocation}.$   
 $(\text{LivingRoom} \sqcap \geq 2 \text{ contains}.\text{TeaCup}$   
 $\sqcap \forall \text{hasSoundSensor} . (\text{MeasuredSoundDb} \leq 35[\text{int}]))) ,$

$\text{LivesInBuilding} \circ \text{HomeBuildingOf} \sqsubseteq \text{NextDoorNeighbor}$

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## DL reasoning

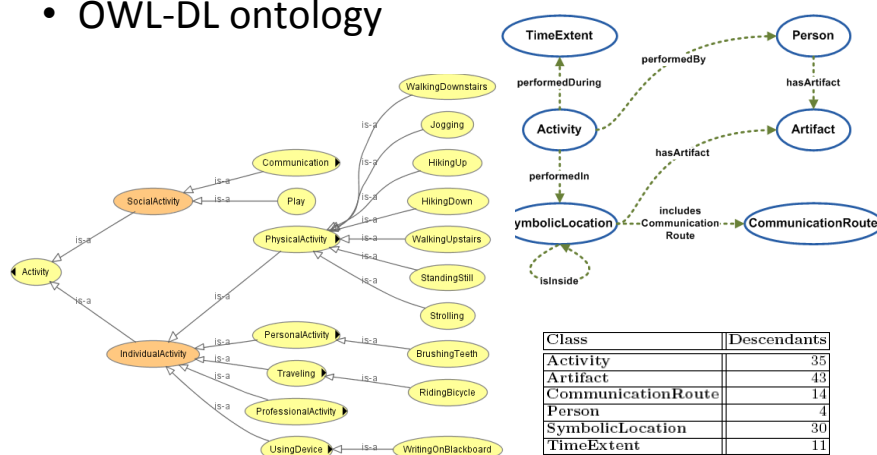
- TBox inconsistency, concept subsumption, classification, equivalence
- Realization
  - Example: Given an ABox context instance description find the most specific class of activities it belongs to
- Class and conjunctive queries
  - Examples:
    - find (in ABox) all instances of the activity "having\_Tea"
    - find (in ABox) all objects that have been used in the kitchen in the last 2 hours

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## Activity Ontology example

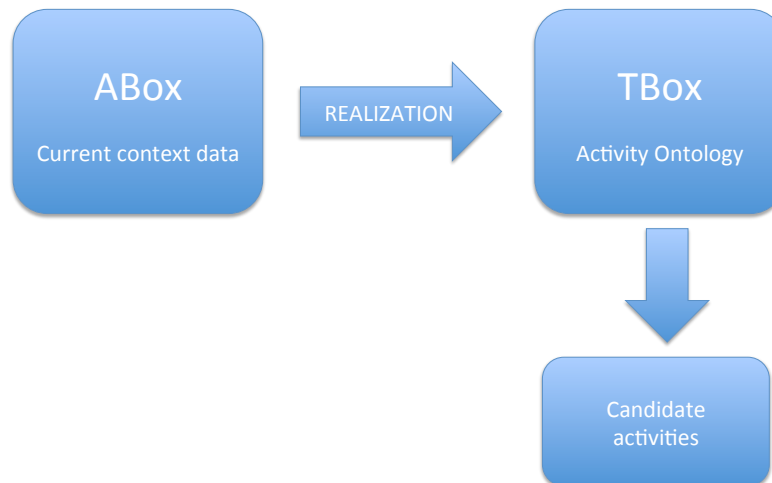
- OWL-DL ontology



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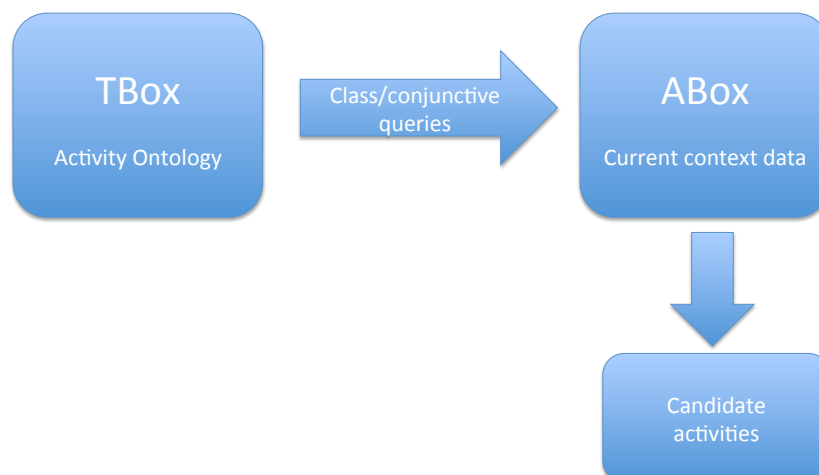
## Basic recognition methods with DLs



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## Basic recognition methods with DLs



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## Example of ontological reasoning

- “Can activity *A* be executed in context *C*?”
  - Add an assertion stating that an instance of *A* is performed in an instance of *C*
  - Perform consistency checking to detect whether the execution *A* is consistent with *C*

`BrushingTeeth  $\sqsubseteq$  PersonalActivity  $\sqcap \forall$  performedIn. (  $\exists$  hasArtifact.Sink )  $\sqcap \dots$`

`RestRoom  $\sqsubseteq$  Room  $\sqcap \exists$  hasArtifact.Sink  $\sqcap \dots$`

`LivingRoom  $\sqsubseteq$  Room  $\sqcap \neg \exists$  hasArtifact.WaterFixture  $\sqcap \dots$`

`BrushingTeeth(CURR_ACT); RestRoom(CURR_LOC_1); LivingRoom(CURR_LOC_2)`

`performedIn(CURR_ACT, CURR_LOC_2); isABoxConsistent()`



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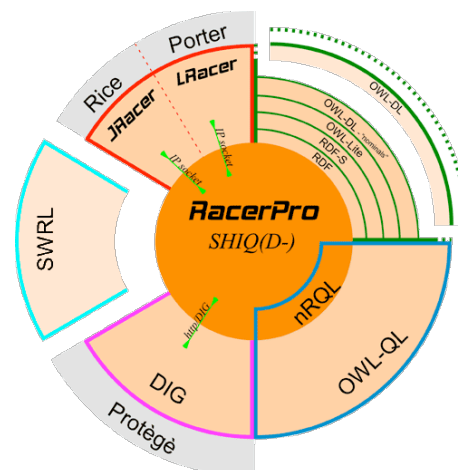
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## Ontology Tools



Fact++

Pellet



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## Drawbacks of existing techniques

- Statistical (data-driven):
  - Scalability
    - with the number of sensors and candidate activities
  - Adaptability
    - change in sensors, position, orientation, environment requires expensive re-training and reconfiguration
  - hard for complex activities
- Symbolic (knowledge-driven):
  - Not well suited to the recognition of low-level activities
  - difficult knowledge engineering task
  - Expressiveness and efficiency issues

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## Evolution of statistical methods

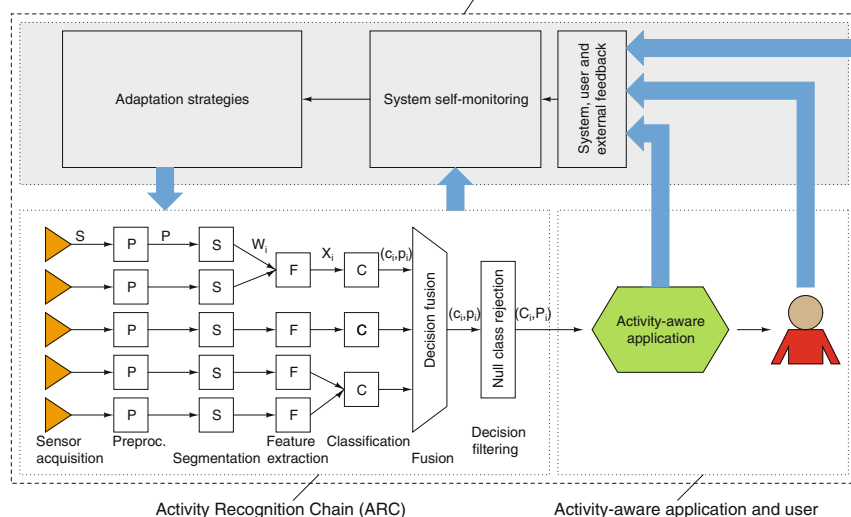


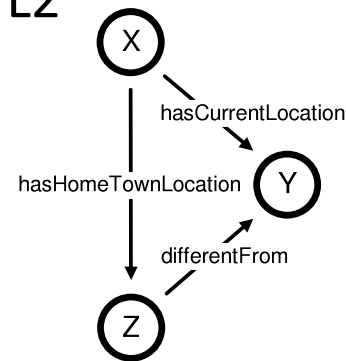
Figure from [D. Roggen et al, JAIHC 2013]

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## Limits of OWL2

- Expressiveness
  - Tree model property
  - Lack of rules support
  - time
  - uncertainty



$\forall X \forall Y \forall Z ( \text{Person}(X) \wedge \text{Location}(Y) \wedge \text{Location}(Z) \wedge$   
 $\text{hasCurrentLocation}(X, Y) \wedge \text{hasHomeTownLocation}(X, Z) \wedge$   
 $\text{differentFrom}(Z, Y) \rightarrow \text{hasCurrentActivity}(X, \text{traveling}) )$

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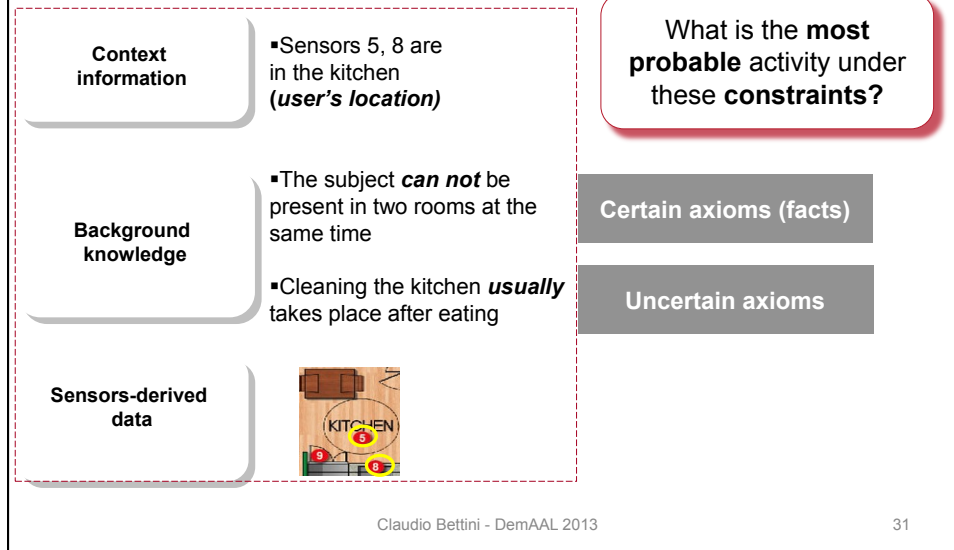
## Augmenting ontological reasoning with rules

- Two approaches
  - tightly coupled: a unified language for rules and ontologies
    - Example: OWL+SWRL
    - Drawback: easy to end up with undecidable logics
  - Loosely coupled: rule-based and ontological reasoning are executed separately
    - Drawback: limited reasoning capabilities (no feedback)

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## Handling uncertainty



## Using Log-linear DLs

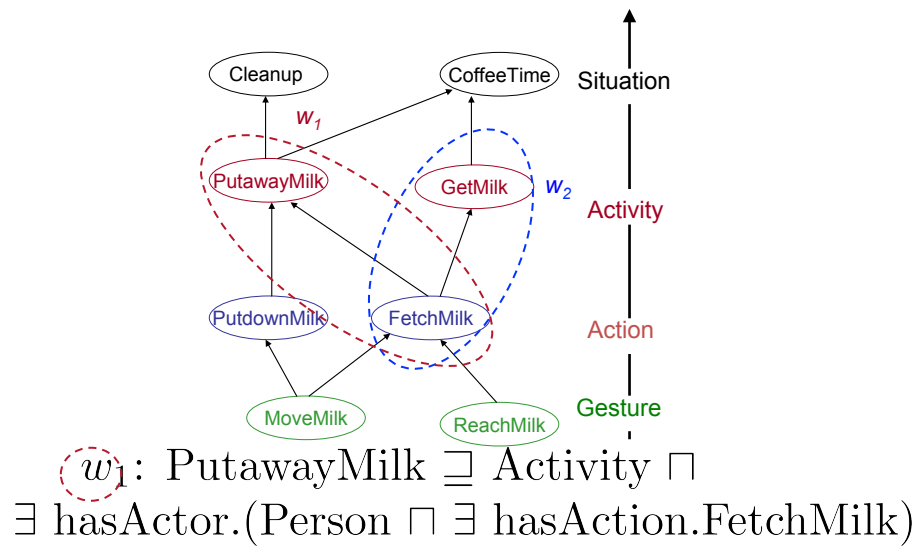
- **Input:** DL *axioms* with and without *weights*
- **Output:** A most probable *consistent* ontology
- **Method:** *Probabilistic* approach to ontological reasoning
  - Maximize:** Sum of *weights*
  - Subject to:** Constraints ensuring *Consistency* of ontology
- **Tool:** Elog Reasoner

[Helaui et al, Ubicomp 2013]

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## Example of weighted axioms



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## Hybrid methods

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## Towards a hybrid framework

- Overall goal: *coupling symbolic and statistical methods to get the best of the two worlds*
- Research issues:
  - Devising a *hybrid intelligent system*
  - Defining a *common ontology* for activities and context data
  - *Flexibility*
  - *Efficiency*

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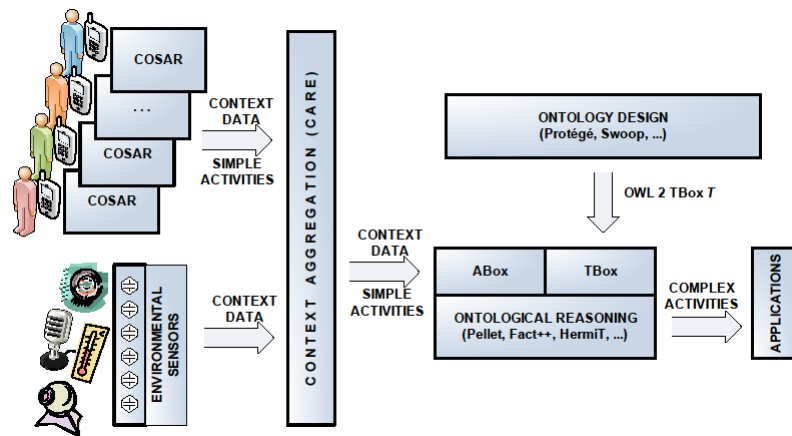
## Different hybrid approaches

1. Ontology used only as a common “vocabulary” for context and activities + possibly for recognition goals guidance
2. Knowledge-driven recognition applied as a second stage after data-driven methods
3. Knowledge-driven methods intertwined with data-driven methods

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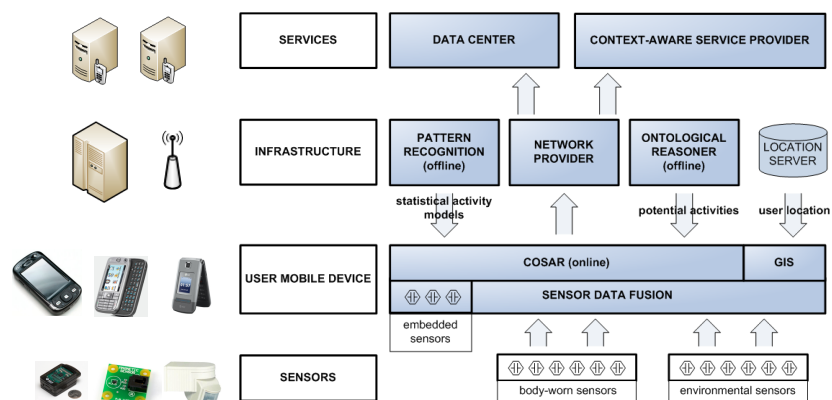
## Hybrid approach 2



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## Hybrid approach 3



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## Hybrid approach 3: example

- Statistical technique applied over ontology-based selected candidates
- Temporal smoothing based on a sliding window

	1	2	3	4	5	6	7	8	9	10
Garden	0	0	0	1	1	1	1	0	0	0
HospitalBuilding	1	0	0	0	0	1	0	1	1	1
Kitchen	1	0	0	0	0	1	0	0	0	1
Laboratory	0	0	0	0	0	1	0	0	0	1
LivingRoom	0	0	0	0	0	1	0	0	0	0
Meadow	0	0	0	1	1	1	1	0	0	0
RestRoom	1	0	0	0	0	1	0	0	0	0
UrbanArea	0	0	0	1	1	1	1	1	1	0
Wood	0	1	1	1	1	1	1	0	0	0

Columns: 1=brushingTeeth; 2=hikingUp; 3=hikingDown; 4=ridingBicycle;  
5=jogging; 6=standingStill; 7=strolling; 8=walkingDownstairs;  
9=walkingUpstairs; 10=writingOnBlackboard

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## Datasets and Experiments

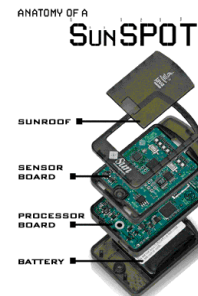
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## COSAR Experimental setup

[Riboni-Bettini, PUC 2011]

- Data acquired from a GPS receiver and two *Sun SPOTs*
  - Programmable in Java
    - Fully capable JME CLDC 1.1 Java VM
    - 180 MHz 32 bit processor, 512K RAM/4M flash memory, IEEE 802.15.4 radio
  - <http://www.sunspotworld.com>
- 5-hours activity data collected by 6 volunteers
- 10 activities



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## COSAR Experimental results

(a) Evaluation of statistical classifiers

Classifier	Accuracy
Bayesian Network	72.95%
C4.5 Decision Tree	66.23%
Multiclass Logistic Regression	80.21%
Naive Bayes	68.55%
SVM	71.81%

(b) Overall accuracy

Classifier	Accuracy
statistical	80.21%
statistical-voted	84.72%
COSAR	89.20%
COSAR-voted	93.44%

(c) Error reduction

versus →	statistical	statistical-voted	COSAR
statistical-voted	22.79%		
COSAR	45.43%	29.32%	
COSAR-voted	66.85%	57.07%	39.26%

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## Ongoing experiments with Log-linear DL and the Opportunity Dataset

**72 sensors of 10 modalities**  
**12 subjects**

<http://www.opportunity-project.eu>

## The SECURE project



- *Intelligent System for Early Diagnosis and Follow-up at Home*
- Partners: Health Telematic company, ICT service provider, Hospital institution specialised on dementia, EveryWare lab
- monitoring 3-10 patients in their homes, non intrusive sensors

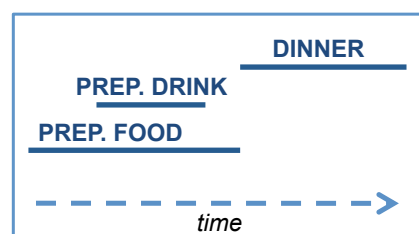
## Research Challenges

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## Research challenges

- Integration of **temporal reasoning** (qualitative and/or quantitative)
  - Among other existing work see [Meditkos et al. COMOREA 2013, Riboni et al. COMOREA 2011]



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## Research challenges

- Devising smart techniques to increase efficiency of ontological reasoning (while dealing with uncertainty and time)
- Recognizing concurrent and interleaved activities (possibly with multiple actors)
- Devising adaptive techniques

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## Research challenges

Enriching context data collection to enhance activity recognition and prediction

by mining *Small Data*

See Deborah Estrin's

TEDMED talk

(<http://tedmed.com/>)



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## References

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*Thanks for your attention*